

Receiver Comparisons

Pulse Width μ s													
	Rudder						Sail Sheet						
	Right Left-right			Right Up/down			Left Up/down			Left Left-right			
	Aileron Channel 1			Elevator Channel 2			Throttle Channel 3			Rudder Channel 4			
PWM range μ s	min	max	μ s	min	max	μ s	min	max	μ s	min	max	μ s	
2.4Ghz GWS R-4S	Man's spec	1250	1750	500	1250	1750	500	1100	1900	800	1250	1750	500
	Test	1278	1734	456	1320	1765	445	1103	1916	813	1305	1765	460
2.4Ghz Spektrum Low rate + AR500		1145	1692	547	1187	1759	572	1093	1855	762	1201	1754	553
Spektrum Dx5e Low rate + OrangeRX		1150	1722	572	1200	1794	594	1100	1891	791	1220	1788	568
35hz Futaba Skysport4		1111	1944	833	1037	1902	865	1215	1870	655	1182	2064	882
27hz Helger Stix-CS		945	1830	885				990	1900	910			

Above values not used below as they are old Tx/Rx, Low rate setting or a "Park Flyer"

2.4Ghz Eurgle 3CH	1145	1864	720				1091	1844	753			
Spektrum Dx5e High Rate + Orange	1060	1812	752	1104	1893	789	1100	1891	791	1139	1887	748
2.4Ghz Spek. Dx5e Hi Rate + AR500	1051	1790	739	1092	1855	763	1093	1856	763	1115	1849	734
2.4Ghz Spektrum Dx7 + AR500	1042	2008	966	1101	1872	771	920	2060	1140	1102	1874	772
2.4Ghz Futaba r617fs	1115	1923	808				1112	1925	813			
2.4Ghz Turnigy TGY9X	1068	1903	835	1063	1907	844	1067	1904	837	1052	1905	853
2.4Ghz HobbyKing HK6DF	1185	1970	785	1125	1890	765	1170	2020	850	1140	1865	725
2.4Ghz Multiplex Light	1042	2140	1098	1042	2140	1098	1042	2068	1026	1063	2139	1076
Max	1185	2140	1098	1125	2140	1098	1170	2068	1140	1140	2139	1075
Min	1042	1790	720	1042	1855	765	1042	1845	755	1063	1849	725
Difference μ s	143	350	378	83	285	333	145	225	385	77	290	350
Pulse Low = 1.04/1.19ms = 0.15ms						High = 1.79/2.14ms = 0.36ms						
Min value = 920 Max = 2140 Range = 1220						Range Min = 0.72ms Max = 1.14ms						

Sheet Travel mm										
Calculated	346 mm/ms		Rudder		Sail Sheet					
			Right Left-right		Right Up/down		Left Up/down		Left Left-right	
			Aileron		Elevator		Throttle		Rudder	
			Channel 1		Channel 2		Channel 3		Channel 4	
			mm		mm		mm		mm	
35hz Futaba Skysport4		288		299		227		305		
2.4Ghz Eurgle 3CH		249				261				
2.4Ghz Spectrum High rate + AR500		158		264		264		254		
2.4Ghz Spectrum Low rate + AR500		189		198		264		191		
Spectrum Dx5e High Rate + Orange		260		273		274		259		
Spectrum Dx5e Low rate + OrangeRX		198		206		274		197		
2.4Ghz GWS R-4S		158		154		281		159		
2.4Ghz Futuba r617fs		280				281				
2.4Ghz Turnigy TGY9X		289		292		290		295		
2.4Ghz HobbyKing HK6DF		272		265		294		251		
27hz Helger Stix-CS		306				315				
2.4Ghz Multiplex Light		380		380		355		372		
2.4Ghz Spektrum Dx7 + AR500		334		266		394		267		
	Max mm	380		380		394		372		
	Min mm	158		264		227		159		
	Difference mm	222		116		167		213		

Sheet travel is calculated using 346mm/ms. It avoids variations due the amount/position of sheet wound on the 25mm drum

Tests using Arm type servos

Servo Rotation in degrees						
Receiver PWM pulse range ms	1.4	1.0	0.9	0.8	0.7	
SailServo 4806	155	111	100	89	78	
SailServo 0918	140	100	90	80	70	
SailServo 0002	133	95	86	76	67	
SailServo 5520	132	94	85	75	66	
SailServo 5509	132	94	85	75	66	
Futuba 3003	127	91	82	73	64	

SailServo range of arm type servos cover from tiny to large. Tested with GWS MT-1 Pro Servo Tester
Futuba 3003 is comparable with 4806

Rotation in degrees													
		Rudder			Sail Sheet								
		Right Left-right			Right Up/down			Left Up/down			Left Left-right		
		Aileron			Elevator			Throttle			Rudder		
		Channel 1			Channel 2			Channel 3			Channel 4		
PWM range us		deg	us/deg	us	deg	us	deg	us	deg	us	deg	us	
2.4Ghz GWS R-4S		42	10.9	456	42	10.6	445	73	11.1	813	43	10.7	460
35hz Futaba Skysport4		77	10.8	835	78	11.0	860	60	11.1	665	80	11.1	885
2.4Ghz Spectrum High rate + AR500		68	10.8	735	68	11.3	765	72	10.6	760	70	10.5	735
Spectrum Dx5e High Rate + Orange		72	10.4	750	72	10.9	785	73	10.8	790	70	10.7	750
2.4Ghz HobbyKing HK6DF		71	11.1	785	72	10.6	765	76	11.2	850	66	11.0	725
27hz Helger Stix-CS		82	10.8	885				82	11.1	910			

Plotting PWM pulse range ms against servo rotation degrees Best fit us/deg = 550/50 = 11.0

Readings accuracy degrees = +/- 1 Pulse = +/- 2